Roy Models of Policy Evaluation

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1. Policy adoption problem

- Suppose a policy is proposed for adoption in a country.
- What can we conclude about the likely effectiveness of the policy in countries?
- Build a model of counterfactuals.

$$Y_1 = \mu_1(X) + U_1$$
 (1)
 $Y_0 = \mu_0(X) + U_0.$



Consider the Basic Generalized Roy Model

- Two potential outcomes (Y_0, Y_1) .
- A choice equation

$$D = \mathbf{1}[\underbrace{\mu_D(Z, V)}_{\text{net utility}} > 0].$$

Observed outcomes:

$$Y = DY_1 + (1 - D)Y_0$$

- Assume $\mu_D(Z, V) = \mu_D(Z) V$.
- This separability plays a key role in the IV (LATE) and discrete choice.
- Can be relaxed, but things look much less traditional the university of

Switching Regression Notation

$$Y = Y_0 + (Y_1 - Y_0)D$$

$$= \mu_0 + (\mu_1 - \mu_0 + U_1 - U_0)D + U_0.$$
(2)

(Quandt, 1958, 1972).

In Conventional Regression Notation

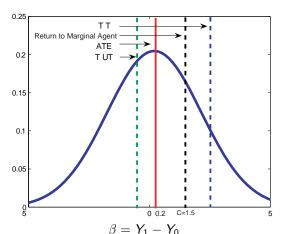
$$Y = \alpha + \beta D + \varepsilon \tag{3}$$

$$\alpha = \mu_0$$
, $\beta = (Y_1 - Y_0) = \mu_1 - \mu_0 + U_1 - U_0$, $\varepsilon = U_0$.

• β is the "treatment effect."



Figure 1: Distribution of gains, a Roy economy



TT= 2.666 =
$$E(Y_1 - Y_0|D=1)$$
, TUT= $-0.632 = E(Y_1 - Y_0|D=0)$
Return to Marginal Agent = $C = 1.5$, ATE = $\mu_1 - \mu_0 = \bar{\beta} = 0.2$

The model

Outcomes

Choice Model

$$Y_1 = \mu_1 + U_1 = \alpha + \bar{\beta} + U_1$$
 $D = \begin{cases} 1 \text{ if } D^* > 0 \\ 0 \text{ if } D^* \le 0 \end{cases}$
 $Y_0 = \mu_0 + U_0 = \alpha + U_0$

General Case

$$(U_1 - U_0) \not\perp\!\!\!\perp D$$

ATE \neq TT \neq TUT



Parameterizing the model

The Researcher Observes (Y, D, C)

$$Y = \alpha + \beta D + U_0$$
 where $\beta = Y_1 - Y_0$

Parameterization

$$\alpha = 0.67 \quad (U_1, U_0) \sim N(\mathbf{0},) \quad D^* = Y_1 - Y_0 - C$$
 $\bar{\beta} = 0.2 \quad = \begin{bmatrix} 1 & -0.9 \\ -0.9 & 1 \end{bmatrix} \quad C = 1.5$



- In the case when $U_1 = U_0 = \varepsilon_0$, simple least squares regression of Y on D subject to a **selection bias** if ε_0 determines D.
- Notice that in a Roy model where $D=1(Y_1-Y_0\geq 0)$ and $U_1=U_0$, $D=1(\mu_1(x)-\mu_0(x)\geq 0)$ where $\mu_1(\cdot)$ and $\mu_0(\cdot)$ depend on X=x.
- "Regression discontinuity" at set of points $x \in \{x | \mu_1(x) \mu_0(x) = 0\}.$
- If

$$D = 1(Y_1 - Y_0 - C \ge 0)$$

$$C = \mu_C(Z) + U_C$$

there would be selection bias if $U_0 \not\perp\!\!\!\perp U_C$.



- Upward biased for β if $Cov(D, \varepsilon_0) > 0$.
- In the example, if $Cov(\varepsilon_0, U_C) < 0$, you get upward bias for OLS. If $Cov(\varepsilon_0, U_C) > 0$, OLS is downward biased.
- **Prove.** How does this covariance relate to the question of whether a country is a meritocracy?



- Three main approaches have been adopted to solve this problem:
 - Selection models
 - 2 Instrumental variable models (experiments; RDD is local IV)
 - **3** Matching: assumes that $\varepsilon \perp \!\!\! \perp D \mid X$.
- Matching is just nonparametric least squares and assumes access to rich data which happens to guarantee this condition.



Instrumental Variables in Case I, the traditional case: β is a constant

• If there is an instrument Z, with the property that

$$Cov(Z, D) \neq 0 \tag{4}$$

$$Cov(Z, \varepsilon) = 0,$$
 (5)

then

plim
$$\hat{\beta}_{IV} = \frac{\text{Cov}(Z, Y)}{\text{Cov}(Z, D)} = \beta.$$

• If other instruments exist, each identifies the same β .



Case II, heterogeneous response case: β is a random variable even conditioning on X

Sorting bias

or sorting on the gain which is distinct from sorting on the level.

Essential heterogeneity

$$Cov(\beta, D) \neq 0$$
.

Suppose (4), (5) and

$$Cov(Z,\beta) = 0. (6)$$

• Can we identify the mean of $(Y_1 - Y_0)$ using IV?



- In general we cannot (Heckman and Robb, 1985).
- Let

$$\bar{\beta} = (\mu_1 - \mu_0)$$

$$\beta = \bar{\beta} + \eta$$

$$U_1 - U_0 = \eta$$

$$Y = \alpha + \bar{\beta}D + [\varepsilon + \eta D].$$

- Need Z to be uncorrelated with $[\varepsilon + \eta D]$ to use IV to identify $\bar{\beta}$.
- This condition will be satisfied if policy adoption is made without knowledge of $\eta (= U_1 U_0)$.
- If decisions about D are made with partial or full knowledge of η , IV does not identify $\bar{\beta}$.
- Crucial Question: What is the agent's information set?

The IV condition is

$$E[\varepsilon + \eta D \mid Z] = 0.$$

- $E(\varepsilon \mid Z) = 0$, $E(\eta \mid Z) = 0$.
- Even if $\eta \perp \!\!\! \perp Z$, $\eta \not \perp \!\!\! \perp Z \mid D = 1$.
- $E(\eta D \mid Z) = E(\eta \mid D = 1, Z) \Pr(D = 1 \mid Z)$.
- But $E(\eta \mid Z, D=1) \neq 0$, in general, if agents have some information about the gains.



- Draft Lottery example (Heckman, 1997).
- Linear IV does not identify ATE or any standard treatment parameters.



Examples

$$D=1(\mu_D(z)>V)$$

(Notice: lower case z is a number; Z is a random variable.)

Example:

$$\mu_D(z) = \gamma z$$

$$(V \perp \!\!\! \perp Z) \mid X$$
.

The propensity score or probability of selection into D=1:

$$P(z) = \Pr(D = 1 \mid Z = z) = \Pr(\gamma z > V) = F_V(\gamma z)$$

 F_V is the distribution of V.



Generalized Roy model

$$U_1 \neq U_0$$

$$D = \mathbf{1}[Y_1 - Y_0 - C \ge 0]$$

Costs
$$C = \mu_C(W) + U_C$$

 $Z = (X, W)$
 $\mu_D(Z) = \mu_1(X) - \mu_0(X) - \mu_C(W)$
 $V = -(U_1 - U_0 - U_C)$.



Heterogeneous response model

In a general model with heterogenous responses, specification of P(Z) and relationship with the rest of the model plays an essential role.

$$E = (\eta D|Z = z)$$

= $E(\eta|D = 1, Z = z)Pr(D = 1|Z = z)$
= $E(\eta|\gamma z \ge V, Z = z)Pr(D = 1|Z = z)$

If F_V is weakly monotonic,

$$= E(\eta | F_V(\gamma z) > F_V(V), Z = z) Pr(D = 1 | Z = z).$$



Because
$$Z \perp \!\!\! \perp \eta | X$$

$$E(\eta | F_V(\gamma z) \geq F_V(V), Z = z)$$

$$= E(\eta | F_V(\gamma z) \geq F_V(V))$$

$$P(z) = F_V(\gamma z) \text{ "Propensity Score"}$$

$$U_D = F_V(V) \text{ "Uniform Random Variable"}$$

$$E(\eta D | Z = z, D = 1)$$

$$= E(\eta | P(z) \geq U_D) P(z).$$

 Probability of selection enters this term, even though we use only one component of Z as an instrument.



•	Selection r	models co	ntrol for t	his depen	dence ind	uced by	choice.



Selection models

Assume

$$(U_1, U_0, V) \perp \!\!\! \perp Z \tag{7}$$

[Alternatively $(\varepsilon, \eta, V) \perp \!\!\! \perp Z$].

$$\eta = (U_1 - U_0), \, \varepsilon = U_0 \tag{8}$$

$$E(Y | D = 0, Z = z) = E(Y_0 | D = 0, Z = z)$$

= $\alpha + E(U_0 | \gamma z < V)$

$$E(Y \mid D = 0, Z = z) = \alpha + K_0(P(z))$$

control function



$$E(Y \mid D = 1, Z = z) = E(Y_1 \mid D = 1, Z = z)$$

$$= \alpha + \bar{\beta} + E(U_1 \mid \gamma z > V)$$

$$= \alpha + \bar{\beta} + \underbrace{K_1(P(z))}_{\text{control function}}$$

- $K_0(P(z))$ and $K_1(P(z))$ are control functions in the sense of Heckman and Robb (1985, 1986).
- P(z) is an essential ingredient in both matching and IV:
- Matching: $K_1(P(z)) = K_0(P(z))$. Why? $E(U_1|Z) = E(U_0|Z)$.
- Matching balances
- It may or may not be true that $E(U_1|Z) = 0$ or $E(U_2|Z) = 0$.
- Matching differences out the common term.

