

# IV Weights and Yitzhaki's Theorem

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## Digression: Yitzhaki's theorem and extensions

### Theorem 1

Assume  $(Y, X)$  i.i.d.  $E(|Y|) < \infty$   $E(|X|) < \infty$

$$\mu_Y = E(Y) \quad \mu_X = E(X)$$

$$E(Y | X) = g(X)$$

Assume  $g'(X)$  exists and  $E(|g'(X)|) < \infty$ .

## Yitzhaki's theorem

### Theorem 2 (cont.)

Then,

$$\frac{\text{Cov}(Y, X)}{\text{Var}(X)} = \int_{-\infty}^{\infty} g'(t) \omega(t) dt,$$

where

$$\begin{aligned}\omega(t) &= \frac{1}{\text{Var}(X)} \int_t^{\infty} (x - \mu_X) f_X(x) dx \\ &= \frac{1}{\text{Var}(X)} E(X - \mu_X \mid X > t) \Pr(X > t).\end{aligned}$$

$$Y = \pi X + \eta,$$

$$\pi = \frac{\text{Cov}(Y, X)}{\text{Var}(X)}.$$

## Proof of Yitzhaki's theorem

Proof.

$$\begin{aligned}\text{Cov}(Y, X) &= \text{Cov}(E(Y | X), X) = \text{Cov}(g(X), X) \\ &= \int_{-\infty}^{\infty} g(t)(t - \mu_X) f_X(t) dt\end{aligned}$$

where t is an argument of integration.

cont.

Integration by parts:

$$\begin{aligned}\text{Cov}(Y, X) &= g(t) \int_{-\infty}^t (x - \mu_X) f_X(x) dx \Big|_{-\infty}^{\infty} \\ &\quad - \int_{-\infty}^{\infty} g'(t) \int_{-\infty}^t (x - \mu_X) f_X(x) dx dt \\ &= \int_{-\infty}^{\infty} g'(t) \int_t^{\infty} (x - \mu_X) f_X(x) dx dt,\end{aligned}$$

since  $E(X - \mu_X) = 0$ .

cont.

Therefore,

$$\text{Cov}(Y, X) = \int_{-\infty}^{\infty} g'(t) E(X - \mu_X \mid X > t) \Pr(X > t) dt.$$

∴ Result follows with

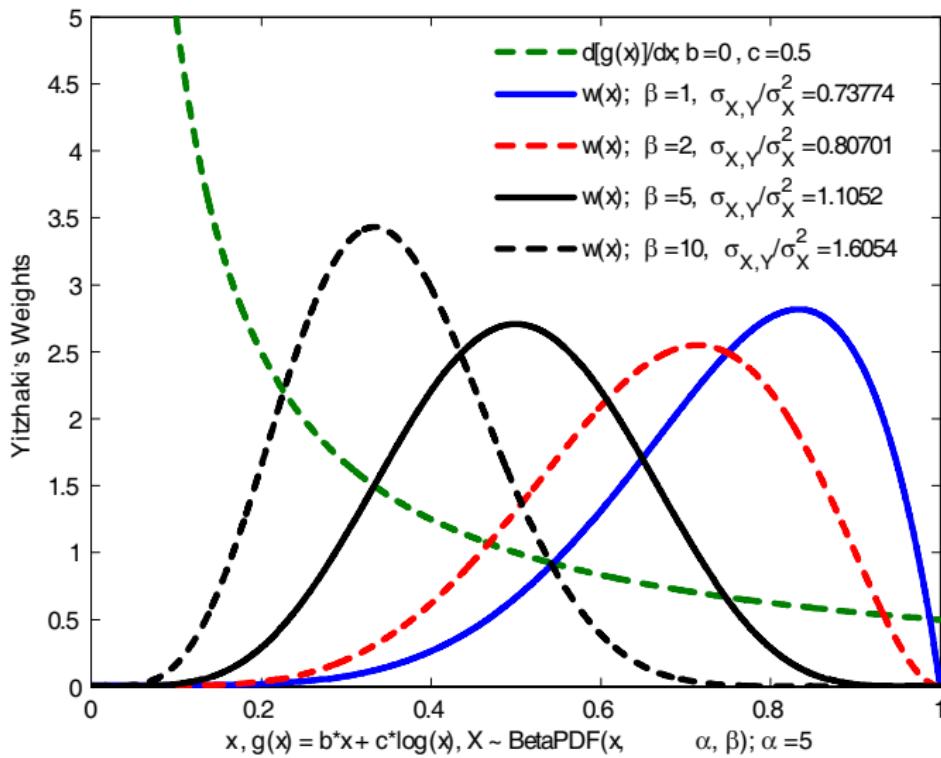
$$\omega(t) = \frac{1}{Var(X)} E(X - \mu_X \mid X > t) \Pr(X > t)$$



- Weights positive.
- Integrate to one (use integration by parts formula).
- = 0 when  $t \rightarrow \infty$  and  $t \rightarrow -\infty$ .
- Weight reaches its peak at  $t = \mu_X$ , if  $f_X$  has density at  $x = \mu_X$ :

$$\begin{aligned}\frac{d}{dt} \int_t^\infty (x - \mu_X) f_X(x) dx dt &= -(t - \mu_X) f_X(t) \\ &= 0 \quad \text{at } t = \mu_X.\end{aligned}$$

## Yitzhaki's weights for $X \sim \text{BetaPDF}(x, \alpha, \beta)$



$$E(Y|X=x) = g(x) \Rightarrow \frac{Cov(X, Y)}{Var(X)} = \int_{-\infty}^{\infty} g'(t)w(t)dx$$

$$w(t) = \frac{1}{Var(X)} E(X|X > t) \cdot \Pr(X > t)$$

$$\mathbf{X} \sim BetaPDF(x, \alpha, \beta) = \frac{x^{\alpha-1}(1-x)^{\beta-1}}{B(\alpha, \beta)}; \ \alpha = 5;$$

$$\mathbf{g(x)} = \mathbf{0.5 \cdot x + 0.5 \cdot log(X)}$$

- Can apply Yitzhaki's analysis to the treatment effect model

$$Y = \alpha + \beta D + \varepsilon$$

- $P(Z)$ , the propensity score is the instrument:

$$E(Y | Z = z) = E(Y | P(Z) = p)$$

$$\begin{aligned}
 E(Y | P(Z) = p) &= \alpha + E(\beta D | P(Z) = p) \\
 &= \alpha + E(\beta | D = 1, P(Z) = p) p \\
 &= \alpha + E(\beta | P(Z) > U_D, P(Z) = p) p \\
 &= \alpha + E(\beta | p > U_D) p \\
 &= \underbrace{\alpha + \int_0^p \beta \int_0^p f(\beta, u_D) du_D}_{g(p)}
 \end{aligned}$$

- Derivative with respect to  $p$  is MTE.
- $g'(p) = \text{MTE}$  and weights as before.

- Under uniformity,

$$\begin{aligned}\frac{\partial E(Y | P(Z) = p)}{\partial p} &= E(Y_1 - Y_0 | U_D = u_D) \\ &= \Delta^{MTE}(u_D).\end{aligned}$$

- More generally, it is LIV =  $\frac{\partial E(Y|P(Z)=p)}{\partial p}$ .
- Yitzhaki's result does not rely on uniformity; true of any regression of  $Y$  on  $P$ .
- Estimates a weighted net effect.
- The expression can be generalized.
- It produces Heckman-Vytlaclil weights.

## The Heckman-Vytlačil weight as a Yitzhaki weight

Consider a general function of  $Z$ ,  $J(Z)$ .

Proof.

$$\begin{aligned}\text{Cov}(J(Z), Y) &= E(Y \cdot \tilde{J}) = E(E(Y | Z) \cdot \tilde{J}(Z)) \\ &= E(E(Y | P(Z)) \cdot \tilde{J}(Z)) \\ &= E(g(P(Z)) \cdot \tilde{J}(Z)).\end{aligned}$$

$$\begin{aligned}\tilde{J} &= J(Z) - E(J(Z) | P(Z) \geq u_D), \\ E(Y | P(Z)) &= g(P(Z)).\end{aligned}$$

cont.

$$\begin{aligned}\text{Cov}(J(Z), Y) &= \int_0^1 \int_{\underline{J}}^{\bar{J}} g(u_D) \tilde{j} f_{P,J}(u_D, j) \, dj \, du_D \\ &= \int_0^1 g(u_D) \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(u_D, j) \, dj \, du_D.\end{aligned}$$

cont.

Use integration by parts:

$$\begin{aligned} & \text{Cov}(J(Z), Y) \\ &= g(u_D) \int_0^{u_D} \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) dj dp \Big|_0^1 \\ &\quad - \int_0^1 g'(u_D) \int_0^{u_D} \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) dj dp du_D \\ &= \int_0^1 g'(u_D) \int_{u_D}^1 \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) dj dp du_D \\ &= \int_0^1 g'(u_D) E\left(\tilde{J}(Z) \mid P(Z) \geq u_D\right) \Pr(P(Z) \geq u_D) du_D. \end{aligned}$$



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cont.

Thus:

$$g'(u_D) = \frac{\partial E(Y | P(Z) = p)}{\partial P(Z)} \Big|_{p=u_D} = \Delta^{\text{MTE}}(u_D).$$



- Under our assumptions the Yitzhaki weights and ours are equivalent.

$$\text{Cov}(J(Z), Y) \tag{1}$$

$$= \int_0^1 \Delta^{\text{MTE}}(u_D) E(J(Z) - E(J(Z)) | P(Z) \geq u_D) \Pr(P(Z) \geq u_D) du_D.$$

- Using (1),

$$\begin{aligned} \text{Cov}(J(Z), Y) &= E(Y \cdot \tilde{J}) = E(E(Y | Z) \cdot \tilde{J}(Z)) \\ &= E(E(Y | P(Z)) \cdot \tilde{J}(Z)) \\ &= E(g(P(Z)) \cdot \tilde{J}(Z)). \end{aligned}$$

- The third equality follows from index sufficiency and  
 $\tilde{J} = J(Z) - E(J(Z) | P(Z) \geq u_D)$ ,  
where  $E(Y | P(Z)) = g(P(Z))$ .
- Writing out the expectation and assuming that  $J(Z)$  and  $P(Z)$  are continuous random variables with joint density  $f_{P,J}$  and that  $J(Z)$  has support  $[\underline{J}, \bar{J}]$ ,

$$\begin{aligned}\text{Cov}(J(Z), Y) &= \int_0^1 \int_{\underline{J}}^{\bar{J}} g(u_D) \tilde{j} f_{P,J}(u_D, j) dj du_D \\ &= \int_0^1 g(u_D) \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(u_D, j) dj du_D.\end{aligned}$$

- Using an integration by parts argument as in Yitzhaki (1989) and as summarized in Heckman, Urzua, Vytlacil (2006), we obtain

$$\begin{aligned}
 & \text{Cov}(J(Z), Y) \\
 &= g(u_D) \int_0^{u_D} \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) \, dj dp \Big|_0^1 \\
 &\quad - \int_0^1 g'(u_D) \int_0^{u_D} \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) \, dj dp du_D \\
 &= \int_0^1 g'(u_D) \int_{u_D}^1 \int_{\underline{J}}^{\bar{J}} \tilde{j} f_{P,J}(p, j) \, dj dp du_D \\
 &= \int_0^1 g'(u_D) E\left(\tilde{j}(Z) \mid P(Z) \geq u_D\right) \Pr(P(Z) \geq u_D) \, du_D,
 \end{aligned}$$

which is then exactly the expression given in (1), where

$$g'(u_D) = \frac{\partial E(Y \mid P(Z) = p)}{\partial P(Z)} \Big|_{p=u_D} = \Delta^{\text{MTE}}(u_D).$$

## Separable choice model

$$\Delta_J^{IV} = \int_0^1 \Delta^{MTE}(u_D) \omega_{IV}^J(u_D) du_D \quad (2)$$

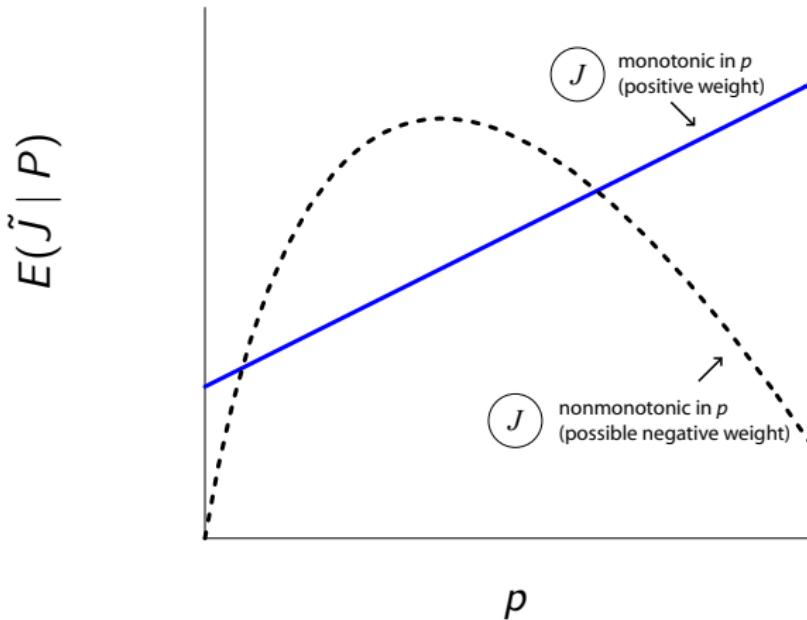
$$\omega_{IV}^J(u_D) = \frac{E(J(Z) - \bar{J}(Z) \mid P(Z) > u_D) \Pr(P(Z) > u_D)}{\text{Cov}(J(Z), D)}. \quad (3)$$

$J(Z)$  and  $P(Z)$  do not have to be continuous random variables.

Functional forms of  $P(Z)$  and  $J(Z)$  are general.

- Dependence between  $J(Z)$  and  $P(Z)$  gives shape and sign to the weights.
- If  $J(Z) = P(Z)$ , then weights obviously non-negative.
- If  $E(J(Z) - \bar{J}(Z) | P(Z) \geq u_D)$  not monotonic in  $u_D$ , weights can be negative.

$$\tilde{J} = J - E(J)$$



Therefore, with positive (or negative) regression, can get negative IV weight.

When  $J(Z) = P(Z)$ , weight (3) follows from Yitzhaki (1989).

- He considers a regression function  $E(Y | P(Z) = p)$ .
- Linear regression of  $Y$  on  $P$  identifies

$$\beta_{Y,P} = \int_0^1 \left[ \frac{\partial E(Y | P(Z) = p)}{\partial p} \right] \omega(p) dp,$$

$$\omega(p) = \frac{\int_p^1 (t - E(P)) dF_P(t)}{Var(P)}.$$

- This is the weight (3) when  $P$  is the instrument.
- This expression **does not** require uniformity or monotonicity for the model; consistent with 2-way flows.

## Understanding the structure of the IV weights

Recapitulate:

$$\Delta_{\text{IV}}^J = \int \Delta^{\text{MTE}}(u_D) \omega_{\text{IV}}^J(u_D) du_D$$
$$\omega_{\text{IV}}^J(u_D) = \frac{\int (j - E(J(Z))) \int_{u_D}^1 f_{J,P}(j, t) dt dj}{\text{Cov}(J(Z), D)} \quad (4)$$

- The weights are always positive if  $J(Z)$  is monotonic in the scalar  $Z$ .
- In this case  $J(Z)$  and  $P(Z)$  have the same distribution and  $f_{J,P}(j, t)$  collapses to a single distribution.

- The possibility of negative weights arises when  $J(Z)$  is not a monotonic function of  $P(Z)$ .
- It can also arise when there are two or more instruments, and the analyst computes estimates with only one instrument or a combination of the  $Z$  instruments that is not a monotonic function of  $P(Z)$  so that  $J(Z)$  and  $P(Z)$  are not perfectly dependent.

- The weights can be constructed from data on  $(J, P, D)$ .
- Data on  $(J(Z), P(Z))$  pairs and  $(J(Z), D)$  pairs (for each  $X$  value) are all that is required.